

# Correctness of Automatic Differentiation via Diffeologies and Categorical Gluing

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Higher-order language, inductive types



Denotational semantics



Correctness of Automatic Differentiation via Diffeologies and  
Categorical Gluing



Logical relations argument

⇒ Aim: Bridge the gap between syntactic AD and mathematics

- 1 Language for higher-order AD
- 2 Denotational semantics for a higher-order language
- 3 A gluing construction
- 4 Another example: Jet-based AD

# Simple higher-order language

$\tau, \sigma, \rho ::=$	types
<b>real</b>	real numbers
$(\tau_1 * \dots * \tau_n)$	finite product
$\{\ell_1 \tau_1 \mid \dots \mid \ell_n \tau_n\}$	variant
$\tau \rightarrow \sigma$	function
<b>list</b> ( $\tau$ )	list

$\Rightarrow$  Higher-order

$\Rightarrow$  Inductive types

# Simple higher-order language

$t, s, r ::=$

|  $x$

|  $\underline{c} \mid t + s \mid t * s \mid \zeta(t)$

|  $\langle t_1, \dots, t_n \rangle \mid \mathbf{case\ } t \mathbf{ of} \langle x_1, \dots, x_n \rangle \rightarrow s$

|  $\lambda x. t \mid t\ s$

|  $\tau.l\ t$

|  $\mathbf{case\ } t \mathbf{ of} \{l_1\ x_1 \rightarrow s_1 \mid \dots \mid l_n\ x_n \rightarrow s_n\}$

|  $[] \mid t :: s$

|  $\mathbf{fold}\ (x_1, x_2). t \mathbf{ over}\ s \mathbf{ from}\ r$

terms

variable

operations/constants

tuples/pattern matching

function abstraction/app.

variant constructor

pattern matching: variants

empty list and cons

list fold

## Goal of traditional AD

Given  $f \stackrel{\text{def}}{=} f_1; f_2; \dots; f_n : \mathbb{R}^k \rightarrow \mathbb{R}$ ,

compute  $\nabla f \stackrel{\text{def}}{=} \left( \frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_k} \right)$

using the chain rule,

assuming  $\frac{\partial f_i}{\partial x_j}$  known.

# AD as a source-code transformation

$$\vec{\mathcal{D}}(\mathbf{real}) \stackrel{\text{def}}{=} (\mathbf{real}*\mathbf{real})$$

$$\vec{\mathcal{D}}(\tau \rightarrow \sigma) \stackrel{\text{def}}{=} \vec{\mathcal{D}}(\tau) \rightarrow \vec{\mathcal{D}}(\sigma)$$

$$\vec{\mathcal{D}}((\tau_1 * \dots * \tau_n)) \stackrel{\text{def}}{=} (\vec{\mathcal{D}}(\tau_1) * \dots * \vec{\mathcal{D}}(\tau_n))$$

$$\vec{\mathcal{D}}(\{\ell_1 \tau_1 \mid \dots \mid \ell_n \tau_n\}) \stackrel{\text{def}}{=} \{\ell_1 \vec{\mathcal{D}}(\tau_1) \mid \dots \mid \ell_n \vec{\mathcal{D}}(\tau_n)\}$$

$$\vec{\mathcal{D}}(\mathbf{list}(\tau)) \stackrel{\text{def}}{=} \mathbf{list}(\vec{\mathcal{D}}(\tau))$$

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$$\vec{\mathcal{D}}(\mathbf{list}(\tau)) \stackrel{\text{def}}{=} \mathbf{list}(\vec{\mathcal{D}}(\tau))$$

Non-trivial definition of  $\vec{\mathcal{D}}$  :

$$\vec{\mathcal{D}}(\underline{c}) \stackrel{\text{def}}{=} \langle \underline{c}, 0 \rangle$$

$$\vec{\mathcal{D}}(t + s) \stackrel{\text{def}}{=} \mathbf{case} \vec{\mathcal{D}}(t) \mathbf{of} \langle x, x' \rangle \rightarrow \mathbf{case} \vec{\mathcal{D}}(s) \mathbf{of} \langle y, y' \rangle \rightarrow \langle x + y, x' + y' \rangle$$

$$\vec{\mathcal{D}}(t * s) \stackrel{\text{def}}{=} \mathbf{case} \vec{\mathcal{D}}(t) \mathbf{of} \langle x, x' \rangle \rightarrow \mathbf{case} \vec{\mathcal{D}}(s) \mathbf{of} \langle y, y' \rangle \rightarrow \\ \langle x * y, x * y' + x' * y \rangle$$

$$\vec{\mathcal{D}}(\varsigma(t)) \stackrel{\text{def}}{=} \mathbf{case} \vec{\mathcal{D}}(t) \mathbf{of} \langle x, x' \rangle \rightarrow \mathbf{let} y = \varsigma(x) \mathbf{in} \langle y, x' * y * (1 - y) \rangle$$



Structure preserving definition of  $\bar{\mathcal{D}}$  :

$$\bar{\mathcal{D}}(x) \stackrel{\text{def}}{=} x$$

$$\bar{\mathcal{D}}(\lambda x.t) \stackrel{\text{def}}{=} \lambda x.\bar{\mathcal{D}}(t) \qquad \bar{\mathcal{D}}(ts) \stackrel{\text{def}}{=} \bar{\mathcal{D}}(t) \bar{\mathcal{D}}(s)$$

$$\bar{\mathcal{D}}(\langle t_1, \dots, t_n \rangle) \stackrel{\text{def}}{=} \langle \bar{\mathcal{D}}(t_1), \dots, \bar{\mathcal{D}}(t_n) \rangle$$

$$\bar{\mathcal{D}}(\text{case } t \text{ of } \langle x_1, \dots, x_n \rangle \rightarrow s) \stackrel{\text{def}}{=} \text{case } \bar{\mathcal{D}}(t) \text{ of } \langle x_1, \dots, x_n \rangle \rightarrow \bar{\mathcal{D}}(s)$$

$$\bar{\mathcal{D}}(\tau.l t) \stackrel{\text{def}}{=} \bar{\mathcal{D}}(\tau).l \bar{\mathcal{D}}(t) \qquad \bar{\mathcal{D}}([]) \stackrel{\text{def}}{=} [] \qquad \bar{\mathcal{D}}(t :: s) \stackrel{\text{def}}{=} \bar{\mathcal{D}}(t) :: \bar{\mathcal{D}}(s)$$

$$\bar{\mathcal{D}}(\text{case } t \text{ of } \{ \ell_1 x_1 \rightarrow s_1 \mid \dots \mid \ell_n x_n \rightarrow s_n \}) \stackrel{\text{def}}{=} \\ \text{case } \bar{\mathcal{D}}(t) \text{ of } \{ \ell_1 x_1 \rightarrow \bar{\mathcal{D}}(s_1) \mid \dots \mid \ell_n x_n \rightarrow \bar{\mathcal{D}}(s_n) \}$$

$$\bar{\mathcal{D}}(\text{fold } (x_1, x_2).t \text{ over } s \text{ from } r) \stackrel{\text{def}}{=} \text{fold } (x_1, x_2).\bar{\mathcal{D}}(t) \text{ over } \bar{\mathcal{D}}(s) \text{ from } \bar{\mathcal{D}}(r)$$

Structure preserving definition of  $\vec{D}$  :

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Lemma (Well-typedness and functoriality of  $\vec{D}$ )

- ▷ If  $\Gamma \vdash t : \tau$  then  $\vec{D}(\Gamma) \vdash \vec{D}(t) : \vec{D}(\tau)$
- ▷ If  $\vec{D}(t)[u/x] = \vec{D}(t)[\vec{D}(u)/x]$

# AD as a source-code transformation (cont.)

## Example (Inner product)

$$\Gamma \vdash t \cdot_n s \stackrel{\text{def}}{=} \text{case } t \text{ of } \langle z_1, \dots, z_n \rangle \rightarrow$$
$$\text{case } s \text{ of } \langle y_1, \dots, y_n \rangle \rightarrow z_1 * y_1 + \dots + z_n * y_n : \text{real}$$

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## Example ( $x_1 : \mathbb{R}, x_2 : \mathbb{R} \vdash g : \mathbb{R}$ )

- $\triangleright \vec{D}(g)((x_1, 1), (x_2, 0)) \stackrel{?}{=} (g(x_1, x_2), \frac{\partial g(x_1, x_2)}{\partial x}(x_1))$
- $\triangleright \vec{D}(g)((x_1, 0), (x_2, 1)) \stackrel{?}{=} (g(x_1, x_2), \frac{\partial g(x_1, x_2)}{\partial x}(x_2)).$

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$$\triangleright \vec{D}(g)((x_1, x'_1), (x_2, x'_2)) \stackrel{?}{=} (g(x_1, x_2), x'_1 \cdot \frac{\partial g(x_1, x_2)}{\partial x}(x_1) + x'_2 \cdot \frac{\partial g(x_1, x_2)}{\partial x}(x_2))$$

# Main theorem: Correctness

## Semantic correctness of $\vec{\mathcal{D}}$

$\tau$  : ground type

$\Gamma$  : context with ground types only

$\Gamma \vdash t : \tau$  possibly with higher-order subterms

The syntactic translation  $\vec{\mathcal{D}}$  coincides with the tangent bundle functor (modulo canonical isomorphisms):

$$\begin{array}{ccc} \llbracket \vec{\mathcal{D}}(\Gamma) \rrbracket & \xrightarrow{\llbracket \vec{\mathcal{D}}(t) \rrbracket} & \llbracket \vec{\mathcal{D}}(\tau) \rrbracket \\ \cong \downarrow & & \downarrow \cong \\ \mathcal{T}(\llbracket \Gamma \rrbracket) & \xrightarrow{\mathcal{T}(\llbracket t \rrbracket)} & \mathcal{T}(\llbracket \tau \rrbracket) \\ \uparrow & & \uparrow \\ \text{Tangent bundle} & & \text{Denotational semantics} \end{array}$$

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# Denotational semantics for a first-order language

## Definition (*CartSp*)

- ▷  $objects(\mathbf{CartSp})$  : Euclidean spaces  $\mathbb{R}^n$
- ▷  $morphisms(\mathbf{CartSp})$  : smooth maps  $\mathbb{R}^n \rightarrow \mathbb{R}^m$

$$\llbracket \mathbf{real} \rrbracket = \mathbb{R}$$

$$\llbracket \tau_1 * \dots * \tau_n \rrbracket = \llbracket \tau_1 \rrbracket \times \dots \times \llbracket \tau_n \rrbracket$$

$$\llbracket t + s \rrbracket = \langle \llbracket t \rrbracket, \llbracket s \rrbracket \rangle; +$$

Similarly for the other operators  $*$ ,  $\zeta$ ,  $\dots$

$\Gamma = (x_1 : \tau_1 \dots x_n : \tau_n)$  is interpreted as  $\llbracket \Gamma \rrbracket \stackrel{\text{def}}{=} \prod_{i=1}^n \llbracket \tau_i \rrbracket$ .

Well typed terms  $\Gamma \vdash t : \tau$  are interpreted as smooth functions

$$\llbracket t \rrbracket : \llbracket \Gamma \rrbracket \rightarrow \llbracket \tau \rrbracket.$$



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What about variant and inductive types?

# Denotational semantics for a first-order language

## Definition

A smooth manifold is a space locally homeomorphic to  $\mathbb{R}^n$  for some  $n$ .

## Example

- ▷ A sphere  $\mathbb{S}^2$  is locally homeomorphic to  $\mathbb{R}^2$
- ▷  $\mathbb{R}^2 + \mathbb{R}^3$
- ▷  $\sum_{i \in \mathbb{N}} \mathbb{R}^i$

# Denotational semantics for a first-order language

## Definition (**Man**)

- ▷  $objects(\mathbf{Man})$  : smooth (Hausdorff second-countable) manifolds
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$$[[\tau + \sigma]] = [[\tau]] + [[\sigma]]$$

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## Theorem

**CartSp**, **Man** are not Cartesian-closed categories.

## Definition

A *diffeological space*  $(X, \mathcal{P}_X)$  consists of:

- ▷ a set  $X$
- ▷ for each  $n$  and each open subset  $U$  of  $\mathbb{R}^n$ , a set  $\mathcal{P}_X^U \subseteq [U \rightarrow X]$  of functions, called *plots*

# Diffeological spaces

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such that

All constant functions are plots;

If  $f: V \rightarrow U$  is a smooth function and  $p \in \mathcal{P}_X^U$ , then  $f \circ p \in \mathcal{P}_X^V$ ;

If  $(p_i \in \mathcal{P}_X^{U_i})_{i \in I}$  is a compatible family of plots

$(x \in U_i \cap U_j \Rightarrow p_i(x) = p_j(x))$  and  $(U_i)_{i \in I}$  covers  $U$ , then the gluing  $p: U \rightarrow X: x \in U_i \mapsto p_i(x)$  is a plot.

## Definition

$f: X \rightarrow Y$  is *smooth* if,  $\forall p \in \mathcal{P}_X^U$ , we have that  $f \circ p \in \mathcal{P}_Y^U$ .

# Diffeological spaces (cont.)

## Example (Product diffeologies)

$(X_i)_{i \in I}$  diffeological spaces.

$\prod_{i \in I} X_i$  can be given the *product diffeology* in which  $U$ -plots are  $(p_i)_{i \in I}$  for  $p_i \in \mathcal{P}_{X_i}^U$ .

## Example (Functional diffeology)

$\mathbf{Diff}(X, Y)$  can be given the *functional diffeology* in which  $U$ -plots are  $f: U \rightarrow \mathbf{Diff}(X, Y)$  such that  $(u, x) \mapsto f(u)(x)$  is an element of  $\mathbf{Diff}(U \times X, Y)$ .



# Diffeological spaces (cont.)

## Theorem

The category **Diff** of diffeological spaces is *Cartesian-closed*, *cocomplete*.

# Diffeological spaces (cont.)

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## Proposition (Full embedding of **Man** into **Diff**)

A manifold  $(X, \{\phi_U\}_U)$  is a diffeological space with:

*the same carrier set  $X$*

*plots  $\mathcal{P}_X^U$  are the smooth functions in  $\mathbf{Man}(U, X)$ .*

$X \rightarrow Y$  is **Man-smooth** iff it is **Diff-smooth**.

*The embedding preserves finite products and countable coproducts.*

# Denotational semantics in **Diff**

$$\llbracket \mathbf{real} \rrbracket \stackrel{\text{def}}{=} \mathbb{R}$$

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$$\llbracket \{\ell_1 \tau_1 \mid \dots \mid \ell_n \tau_n\} \rrbracket \stackrel{\text{def}}{=} \llbracket \tau_1 \rrbracket + \dots + \llbracket \tau_n \rrbracket$$

$$\llbracket \tau \rightarrow \sigma \rrbracket \stackrel{\text{def}}{=} \mathbf{Diff}(\llbracket \tau \rrbracket, \llbracket \sigma \rrbracket)$$

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$$\llbracket \tau \rightarrow \sigma \rrbracket \stackrel{\text{def}}{=} \mathbf{Diff}(\llbracket \tau \rrbracket, \llbracket \sigma \rrbracket)$$

$$\llbracket \varsigma(t) \rrbracket(\rho) \stackrel{\text{def}}{=} \varsigma(\llbracket t \rrbracket(\rho)), \text{ where } \rho \in \llbracket \Gamma \rrbracket$$

$$\llbracket \langle t_1, \dots, t_n \rangle \rrbracket(\rho) \stackrel{\text{def}}{=} (\llbracket t_1 \rrbracket(\rho), \dots, \llbracket t_n \rrbracket(\rho))$$

$$\llbracket \lambda x:\tau. t \rrbracket(\rho)(a) \stackrel{\text{def}}{=} \llbracket t \rrbracket(\rho, a) \quad (a \in \llbracket \tau \rrbracket)$$

$$\llbracket \mathbf{case } t \mathbf{ of } \langle \dots \rangle \rightarrow s \rrbracket(\rho) \stackrel{\text{def}}{=} \llbracket s \rrbracket(\rho, \llbracket t \rrbracket(\rho))$$

$$\llbracket ts \rrbracket(\rho) \stackrel{\text{def}}{=} \llbracket t \rrbracket(\rho)(\llbracket s \rrbracket(\rho))$$

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# Initial syntactic category

## Definition

- ▷ *Objects*(**Syn**) : types from our language
- ▷ Morphism  $\tau \rightarrow \sigma$  : a term in context  $x : \tau \vdash t : \sigma$  modulo  $\beta\eta$ -laws. Composition is by substitution.

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## Lemma (Universal Property of **Syn**)

$$\mathbf{Syn} \xrightarrow{\exists! F \text{ pres. } CC, +, Lists} \forall \mathcal{C}, \quad CC \text{ with } +, Lists$$

given a choice of  $F(\mathbf{real}) \in \mathcal{C}, F(\underline{c}), F(+), F(*), F(\zeta)$ .

# Initial syntactic category

## Example (Canonical definition of forward AD)

$\vec{\mathcal{D}}$  arises as a canonical CC functor on **Syn**.

Consider the unique CC functor  $F: \mathbf{Syn} \rightarrow \mathbf{Syn}$  such that

$$F(\mathbf{real}) \stackrel{\text{def}}{=} \mathbf{real} * \mathbf{real}$$

$$F(\underline{c}) \stackrel{\text{def}}{=} \vec{\mathcal{D}}(\underline{c}) = (\underline{c}, \underline{0})$$

$$F(\zeta) \stackrel{\text{def}}{=} \vec{\mathcal{D}}(\zeta(x))$$

$$F(+ ) \stackrel{\text{def}}{=} z : F(\mathbf{real}) * F(\mathbf{real}) \vdash \mathbf{case } z \mathbf{ of } \langle x, y \rangle \rightarrow \vec{\mathcal{D}}(x + y) : F(\mathbf{real})$$

Then  $\forall \tau, x : \tau \vdash t : \sigma$ ,  $F(\tau) = \vec{\mathcal{D}}(\tau)$  and  $F(t) = \vec{\mathcal{D}}(t)$  as morphisms  $F(\tau) \rightarrow F(\sigma)$  in **Syn**.



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$\Rightarrow$  Well-typedness, functoriality, definition on all type constructors of  $\vec{\mathcal{D}}$  for free

# No canonical tangent space on function spaces

## Example

$$\triangleright \vec{\mathcal{D}}((\mathbb{R} \rightarrow \mathbb{R}) \rightarrow \mathbb{R}) = (\mathbb{R}^2 \rightarrow \mathbb{R}^2) \rightarrow \mathbb{R}^2$$

$$\triangleright \vec{\mathcal{D}}(g)(f, \nabla f) = (f; g, \nabla(f; g))$$

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## Idea

Pair a space  $X$  with a chosen tangent bundle  $X'$ .

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Pair a space  $X$  with a chosen tangent bundle  $X'$ .

## Example

$(\mathbb{R}, \mathbb{R}^2, S)$  where  $S \subseteq [\mathbb{R} \rightarrow \mathbb{R}] \times [\mathbb{R} \rightarrow \mathbb{R}^2]$  such that  $S = \{(f, (f, \nabla f)) \mid f: \mathbb{R} \rightarrow \mathbb{R} \text{ smooth}\}$ .

## Definition

- ▷ *Objects*(**GI**) : triples  $(X, X', S)$  where
  - $X$  and  $X'$  are diffeological spaces
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# Glueing category

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## Proposition

**GI** is cartesian closed with coproducts, has list objects, and the projection functor  $\text{proj} : \mathbf{GI} \rightarrow \mathbf{Diff} \times \mathbf{Diff}$  preserves this structure.



# Proof of main theorem (scoring)

$$\begin{array}{ccc} \mathbf{Syn} & \xrightarrow{(\text{id}, \vec{\mathcal{D}}(-))} & \mathbf{Syn} \times \mathbf{Syn} \\ \downarrow \llbracket - \rrbracket & & \downarrow \llbracket - \rrbracket \times \llbracket - \rrbracket \\ \mathbf{Gl} & \xrightarrow{\text{proj}} & \mathbf{Diff} \times \mathbf{Diff} \end{array}$$

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where  $\langle \! \langle - \! \rangle \! \rangle = (\langle \! \langle - \! \rangle \! \rangle_0, \langle \! \langle - \! \rangle \! \rangle_1, S_-)$ , interpreting types  $\tau$  as objects  $(\langle \! \langle \tau \! \rangle \! \rangle_0, \langle \! \langle \tau \! \rangle \! \rangle_1, S_\tau)$ , and terms as morphisms:

- ▷  $\langle \! \langle \mathbf{real} \! \rangle \! \rangle_0 \stackrel{\text{def}}{=} \mathbb{R}$ ,  $\langle \! \langle \mathbf{real} \! \rangle \! \rangle_1 \stackrel{\text{def}}{=} \mathbb{R}^2$  with the relation
- $$S_{\mathbf{real}} \stackrel{\text{def}}{=} \{(f, (f, \nabla f)) \mid f: \mathbb{R} \rightarrow \mathbb{R} \text{ smooth}\}.$$

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- ▷  $(\mathbf{c})_0 \stackrel{\text{def}}{=} \underline{c}$  and  $(\mathbf{c})_1 \stackrel{\text{def}}{=} (\underline{c}, 0)$
- ▷ Interpret  $+$ ,  $\times$ ,  $\zeta$  in the standard way (meaning, like  $\llbracket - \rrbracket$ ) in  $\llbracket - \rrbracket_0$ , but according to the derivatives in  $\llbracket - \rrbracket_1$ , e.g.

$$(\ast)_1((x, x'), (y, y')) \stackrel{\text{def}}{=} (xy, xy' + x'y).$$

# Elementary logical relations argument

Definition (Logical relation  $S_\tau$  between curves in  $[[\tau]]$  and curves in  $[[\vec{\mathcal{D}}(\tau)]]$ )

- ▷  $S_{\text{real}} \stackrel{\text{def}}{=} \{(f, (f, \nabla f)) \mid f: \mathbb{R} \rightarrow \mathbb{R} \text{ smooth}\}$
- ▷  $S_{(\tau * \sigma)} \stackrel{\text{def}}{=} \{((f_1, g_1), (f_2, g_2)) \mid (f_1, f_2) \in S_\tau, (g_1, g_2) \in S_\sigma\}$
- ▷  $S_{\tau \rightarrow \sigma} \stackrel{\text{def}}{=} \{(f_1, f_2) \mid \forall (g_1, g_2) \in S_\tau. (x \mapsto f_1(x)(g_1(x)), x \mapsto f_2(x)(g_2(x))) \in S_\sigma\}$

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## Fundamental Lemma

If  $x_1: \tau_1, \dots, x_n: \tau_n \vdash t: \sigma$  and, for all  $1 \leq i \leq n$ ,  $y_1 \dots y_m: \mathbf{real} \vdash s_i: \tau_i$  is such that  $((f_1, \dots, f_m); [[s_i]], (f_1, \nabla f_1), \dots, f_m, \nabla f_m); [[\vec{\mathcal{D}}(s_i)]] \in S_{\tau_i}$  for all smooth  $f_i: \mathbb{R} \rightarrow \mathbb{R}$ , then  $((f_1, \dots, f_m); [[t^{s_1/x_1, \dots, s_n/x_n}]], (f_1, \nabla f_1, \dots, f_m, \nabla f_m); [[\vec{\mathcal{D}}(t^{s_1/x_1, \dots, s_n/x_n})]])$  is in  $S_\sigma$  for all smooth  $f_i: \mathbb{R} \rightarrow \mathbb{R}$ .

# Main theorem: Correctness

## Semantic correctness of $\vec{\mathcal{D}}$

$\tau$  : ground type

$\Gamma$  : context with ground types only

$\Gamma \vdash t : \tau$  possibly with higher-order subterms

The syntactic translation  $\vec{\mathcal{D}}$  coincides with the tangent bundle functor (modulo canonical isomorphisms):

$$\begin{array}{ccc} \llbracket \vec{\mathcal{D}}(\Gamma) \rrbracket & \xrightarrow{\llbracket \vec{\mathcal{D}}(t) \rrbracket} & \llbracket \vec{\mathcal{D}}(\tau) \rrbracket \\ \cong \downarrow & & \downarrow \cong \\ \mathcal{T}(\llbracket \Gamma \rrbracket) & \xrightarrow{\mathcal{T}(\llbracket t \rrbracket)} & \mathcal{T}(\llbracket \tau \rrbracket) \\ \uparrow & & \uparrow \\ \text{Tangent bundle} & & \text{Denotational semantics} \end{array}$$

- 1 Language for higher-order AD
- 2 Denotational semantics for a higher-order language
- 3 A gluing construction
- 4 Another example: Jet-based AD

# Jet bundle functor

## Definition (Tangent space)

$x \in M$  manifold.

$\mathcal{T}_x M \stackrel{\text{def}}{=} \{ \gamma \in \mathbf{Man}(\mathbb{R}, M) \mid \gamma(0) = x \} / \sim$  where  $\gamma_1 \sim \gamma_2$  iff  $\nabla(\gamma_1; f)(0) = \nabla(\gamma_2; f)(0)$  for all smooth  $f: M \rightarrow \mathbb{R}$ .

## Definition ((1,2)-Jet space)

$J_x^{(1,2)} M \stackrel{\text{def}}{=} \{ \gamma \in \mathbf{Man}(\mathbb{R}, M) \mid \gamma(0) = x \} / \sim$   
where  $\gamma_1 \sim \gamma_2$  iff  $\nabla(\gamma_1; f)(0) = \nabla(\gamma_2; f)(0)$  and  $\nabla^2(\gamma_1; f)(0) = \nabla^2(\gamma_2; f)(0)$  for all smooth  $f: M \rightarrow \mathbb{R}$ .

## Definition ((1,2)-Jet bundle of $M$ )

$J^{(1,2)} M \stackrel{\text{def}}{=} \bigsqcup_{x \in M} J_x^{(1,2)}(M)$ .  
 $J^{(1,2)} : \mathbf{Man} \rightarrow \mathbf{Man}$  is a functor.



Interested in transforming a function  $g: \mathbb{R}^n \rightarrow \mathbb{R}$  into a function  $h: (\mathbb{R} \times \mathbb{R} \times \mathbb{R})^n \rightarrow \mathbb{R} \times \mathbb{R} \times \mathbb{R}$  in such a way that for any  $f_1 \dots f_n: \mathbb{R} \rightarrow \mathbb{R}$ ,

$$(f_1, \nabla f_1, \nabla^2 f_1, \dots, f_n, \nabla f_n, \nabla^2 f_n); h = \\ ((f_1 \dots f_n); g, \nabla((f_1, \dots, f_n); g), \nabla^2((f_1, \dots, f_n); g)).$$

An intuition for  $h$  can be given in terms of triple numbers.

## Example

$g: \mathbb{R}^2 \rightarrow \mathbb{R}$  is a smooth function, then

$$h((x_1, 1, 0), (x_2, 0, 0)) = (g(x_1, x_2), \frac{\partial g(x, x_2)}{\partial x}(x_1), \frac{\partial^2 g(x, x_2)}{\partial x^2}(x_1)),$$

$$h((x_1, 0, 0), (x_2, 1, 0)) = (g(x_1, x_2), \frac{\partial g(x_1, x)}{\partial x}(x_2), \frac{\partial^2 g(x_1, x)}{\partial x^2}(x_2)) \text{ and}$$

$$h((x_1, 1, 0), (x_2, 1, 0)) = (g(x_1, x_2), \frac{\partial g(x_1, x)}{\partial x}(x_2), \frac{\partial^2 g(x, x_2)}{\partial x^2}(x_1) + \frac{\partial^2 g(x_1, x)}{\partial x^2}(x_2) + 2 \frac{\partial^2 g(x, y)}{\partial x \partial y}(x_1, x_2)).$$

$$\vec{\mathcal{D}}^2(\mathbf{real}) \stackrel{\text{def}}{=} (\mathbf{real} * \mathbf{real} * \mathbf{real})$$

$$\vec{\mathcal{D}}^2(\tau \rightarrow \sigma) \stackrel{\text{def}}{=} \vec{\mathcal{D}}^2(\tau) \rightarrow \vec{\mathcal{D}}^2(\sigma)$$

$$\vec{\mathcal{D}}^2((\tau_1 * \dots * \tau_n)) \stackrel{\text{def}}{=} (\vec{\mathcal{D}}^2(\tau_1) * \dots * \vec{\mathcal{D}}^2(\tau_n))$$

$$\vec{\mathcal{D}}^2(\{\ell_1 \tau_1 \mid \dots \mid \ell_n \tau_n\}) \stackrel{\text{def}}{=} \{\ell_1 \vec{\mathcal{D}}^2(\tau_1) \mid \dots \mid \ell_n \vec{\mathcal{D}}^2(\tau_n)\}$$

$$\vec{\mathcal{D}}^2(\mathbf{list}(\tau)) \stackrel{\text{def}}{=} \mathbf{list}(\vec{\mathcal{D}}^2(\tau))$$

$$\vec{D}^2(\underline{c}) \stackrel{\text{def}}{=} \langle \underline{c}, 0, 0 \rangle$$

$$\vec{D}^2(t + s) \stackrel{\text{def}}{=} \mathbf{case} \vec{D}^2(t) \mathbf{of} \langle x, x', x'' \rangle \rightarrow \mathbf{case} \vec{D}^2(s) \mathbf{of} \langle y, y', y'' \rangle \rightarrow \langle x + y, x' + y', x'' + y'' \rangle$$

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$$\vec{D}^2(\zeta(t)) \stackrel{\text{def}}{=} \mathbf{case} \vec{D}^2(t) \mathbf{of} \langle x, x', x'' \rangle \rightarrow \mathbf{let} y = \zeta(x) \mathbf{in let} z = y * (1 - y) \mathbf{in} \langle y, x' * z, z * x'' + z * (1 - 2 * y) * x' * x' \rangle$$

# Gluing category for Jet-based AD

Definition (Same as before)

**GI** whose objects are triples  $(X, X', S)$  where  $X$  and  $X'$  are diffeological spaces and  $S \subseteq [\mathbb{R} \rightarrow X] \times [\mathbb{R} \rightarrow X']$  is a relation between their curves. A morphism  $(X, X', S) \rightarrow (Y, Y', T)$  is a pair of smooth functions  $f: X \rightarrow Y$ ,  $f': X' \rightarrow Y'$ , such that if  $(g, g') \in S$  then  $(g; f, g'; f') \in T$ .

Proposition

*The category **GI** is cartesian closed with coproducts, has list objects, and the projection functor  $\text{proj} : \mathbf{GI} \rightarrow \mathbf{Diff} \times \mathbf{Diff}$  preserves this structure.*

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 \mathbf{GI} & \xrightarrow{\text{proj}} & \mathbf{Diff} \times \mathbf{Diff}
 \end{array}$$

$$\begin{array}{ccc}
 \llbracket \vec{\mathcal{D}}^2(\Gamma) \rrbracket & \xrightarrow{\llbracket \vec{\mathcal{D}}^2(t) \rrbracket} & \llbracket \vec{\mathcal{D}}^2(\tau) \rrbracket \\
 \cong \downarrow & & \downarrow \cong \\
 \mathcal{J}^{(1,2)} \llbracket \Gamma \rrbracket & \xrightarrow{\mathcal{J}^{(1,2)} \llbracket t \rrbracket} & \mathcal{J}^{(1,2)} \llbracket \tau \rrbracket
 \end{array}$$

# Conclusion

## Summary

- ▷ **Higher-order** language with **inductive types** with smooth primitives
- ▷ AD as a **source-code transformation**
- ▷ Denotational semantics in **Diff**
- ▷ Proof via categorical gluing
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## Future Work

- ▷ Partiality and recursion (e.g. for recursive NN)
- ▷ Probabilities (e.g. for HMC, VI)
- ▷ Efficient jet-based or reverse-mode implementations (e.g. for full or approximate Hessian computations)

# Reverse-mode AD

$$\overleftarrow{\mathcal{D}}_{\rho}(\mathbf{real}) = (\mathbf{real} * (\mathbf{real} \rightarrow \rho)) \qquad \overleftarrow{\mathcal{D}}_k(\underline{c}) \stackrel{\text{def}}{=} \langle \underline{c}, \lambda z. \langle \underline{0}, \dots, \underline{0} \rangle \rangle$$

$$\overleftarrow{\mathcal{D}}_k(t + s) \stackrel{\text{def}}{=} \mathbf{case} \overleftarrow{\mathcal{D}}_k(t) \mathbf{of} \langle x, x' \rangle \rightarrow \\ \mathbf{case} \overleftarrow{\mathcal{D}}_k(s) \mathbf{of} \langle y, y' \rangle \rightarrow \langle x + y, \lambda z. x' z + y' z \rangle$$

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$$\overleftarrow{\mathcal{D}}_k(\varsigma(t)) \stackrel{\text{def}}{=} \mathbf{case} \overleftarrow{\mathcal{D}}_k(t) \mathbf{of} \langle x, x' \rangle \rightarrow \mathbf{let} y = \varsigma(x) \mathbf{in} \langle y, \lambda z. x' (y * (1 - y) * z) \rangle.$$

# Reverse-mode AD (cont.)

## Theorem (Semantic correctness of $\overline{\mathcal{D}}_k$ )

For any ground  $\tau$ , any first order context  $\Gamma$  and any term  $\Gamma \vdash t : \tau$ , syntactic translation  $t \mapsto \text{evR}_\tau^k(\overline{\mathcal{D}}_k(t)[\text{lamR}_\tau^k(z)/\dots])$  coincides with the tangent bundle functor, modulo these canonical isomorphisms:

$$\begin{array}{ccc} \llbracket \overline{\mathcal{D}}_k(\Gamma) \rrbracket & \xrightarrow{\llbracket \text{lamR}_\tau^k; \overline{\mathcal{D}}_k(t); \text{evR}_\tau^k \rrbracket} & \llbracket \overline{\mathcal{D}}_k(\tau) \rrbracket \\ \phi_{\Gamma,k}^{\overline{\mathcal{D}}_\tau} \downarrow \cong & & \cong \downarrow \phi_{\tau,k}^{\overline{\mathcal{D}}_\tau} \\ \mathcal{T}^k(\llbracket \Gamma \rrbracket) & \xrightarrow{\mathcal{T}^k(\llbracket t \rrbracket)} & \mathcal{T}^k(\llbracket \tau \rrbracket) \end{array}$$

# Reverse-mode AD (cont.)

$\tau = \mathbf{real}$ ,  $\Gamma = x, y : \mathbf{real}$

$x, y : \mathbf{real} \vdash t : \mathbf{real}$  at values  $x = V, y = W$ :

$$\text{evR}_{\mathbf{real}}^2 (\overline{\mathcal{D}}_2(t) [(\text{lamR}_{x:\mathbf{real}}^2 v) / x, (\text{lamR}_{y:\mathbf{real}}^2 w) / y]) [\langle V, \langle \underline{1}, 0 \rangle \rangle / v, \langle W, \langle \underline{0}, \underline{1} \rangle \rangle / w].$$

Indeed,

$$\begin{aligned} & \llbracket \text{evR}_{\mathbf{real}}^2 (\overline{\mathcal{D}}_2(t) [(\text{lamR}_{x:\mathbf{real}}^2 v) / x, (\text{lamR}_{y:\mathbf{real}}^2 w) / y]) [\langle V, \langle \underline{1}, 0 \rangle \rangle / v, \langle W, \langle \underline{0}, \underline{1} \rangle \rangle / w] \rrbracket = \\ & (\llbracket t \rrbracket (\llbracket V \rrbracket, \llbracket W \rrbracket), \partial_1 \llbracket t \rrbracket (\llbracket V \rrbracket, \llbracket W \rrbracket), \partial_2 \llbracket t \rrbracket (\llbracket V \rrbracket, \llbracket W \rrbracket)). \end{aligned}$$

# Diff as a category of concrete sheaves

A concrete site  $\mathcal{C}$  is a subcanonical site with a terminal  $1$  such that

- ▷  $\text{Hom}(1, -) : \mathcal{C} \rightarrow \mathbf{Set}$  is faithful
- ▷ For each covering  $(f_i : D_i \rightarrow D)_{i \in I}$ , the family  $(\text{Hom}(1, f_i) : \text{Hom}(1, D_i) \rightarrow \text{Hom}(1, D))_{i \in I}$  is jointly surjective

A sheaf  $X$  is concrete if for every  $D \in \mathcal{C}$ , the function

$X(D) \ni \phi \mapsto \underline{\phi} : \text{Hom}(1, D) \rightarrow X(1)$  is one-to-one.

# Diff as a category of concrete sheaves (cont.)

Let **Open** be the category of open subsets of  $\mathbb{R}^n$  for all  $n$ , and smooth maps.

## Theorem

**Diff** arises as the category of concrete sheaves on **Open** whose Grothendieck topology is given by the subcanonical coverage given by open coverings.

## Theorem

**Diff** is a Grothendieck quasi-topos. In particular it is Cartesian-closed, complete, cocomplete.

# CartSp, Man are not CCC

## Lemma

*There is no continuous injection  $\mathbb{R}^{d+1} \rightarrow \mathbb{R}^d$ .*

## Proof.

If there were, it would restrict to a continuous injection  $S^d \rightarrow \mathbb{R}^d$ . The Borsuk-Ulam theorem, however, tells us that every continuous  $f: S^d \rightarrow \mathbb{R}^d$  has some  $x \in S^d$  such that  $f(x) = f(-x)$ , which is a contradiction.  $\square$

Let us define the terms:

$$x_0 : \mathbf{real}, \dots, x_n : \mathbf{real} \vdash t_n = \lambda y. x_0 + x_1 * y + \dots + x_n * y^n : \mathbf{real} \rightarrow \mathbf{real}$$

Assuming that **CartSp/Man** is cartesian closed, observe that these get interpreted as injective continuous (because smooth) functions  $\mathbb{R}^n \rightarrow \llbracket \mathbf{real} \rightarrow \mathbf{real} \rrbracket$  in **CartSp** and **Man**.



# CartSp, Man are not CCC (cont.)

## Theorem

**CartSp** is not cartesian closed.

## Proof.

In case **CartSp** were cartesian closed, we would have  $\llbracket \mathbf{real} \rightarrow \mathbf{real} \rrbracket = \mathbf{real}^n$  for some  $n$ . Then, we would get, in particular a continuous injection  $\llbracket t_{n+1} \rrbracket : \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$ , which contradicts the lemma. □

# CartSp, Man are not CCC (cont.)

## Theorem

**Man** is not cartesian closed.

## Proof.

Observe that we have  $\iota_n : \mathbb{R}^n \rightarrow \mathbb{R}^{n+1}; \langle a_0, \dots, a_n \rangle \mapsto \langle a_0, \dots, a_n, 0 \rangle$  and that  $\iota_n; \llbracket t_{n+1} \rrbracket = \llbracket t_n \rrbracket$ . Let us write  $A_n$  for the image of  $\llbracket t_n \rrbracket$  and  $A = \cup_{n \in \mathbb{N}} A_n$ . Then,  $A_n$  is connected because it is the continuous image of a connected set. Similarly,  $A$  is connected because it is the non-disjoint union of connected sets. This means that  $A$  lies in a single connected component of  $\llbracket \mathbf{real} \rightarrow \mathbf{real} \rrbracket$ , which is a manifold with some finite dimension, say  $d$ .

Take some  $x \in \mathbb{R}^{d+1}$  (say,  $0$ ), take some open  $d$ -ball  $U$  around  $\llbracket t_{d+1} \rrbracket(x)$ , and take some open  $d+1$ -ball  $V$  around  $x$  in  $\llbracket t_{d+1} \rrbracket^{-1}(U)$ . Then,  $\llbracket t_{d+1} \rrbracket$  restricts to a continuous injection from  $V$  to  $U$ , or equivalently,  $\mathbb{R}^{d+1}$  to  $\mathbb{R}^d$ , which contradicts the lemma.  $\square$